

## ENHANCED NETWORK LIFETIME USING HYBRID K-MEANS CLUSTERING IN WIRELESS SENSOR NETWORKS

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### ABSTRACT:

Wireless sensor network is a network of energy constrained nodes with the capability of sensing and communication covering a large area. Although WSNs have significant advancements in many areas; maximizing the lifetime of the whole network remains a major obstruction. In this study, an energy efficient clustering protocol based on hybrid K-means algorithm has been proposed for WSN where midpoint algorithm is used to improve initial centroid selection procedure. Midpoint method has been applied for initial CHs selection, instead of choosing initial CHs randomly. It obtains balanced cluster where CHs are uniformly distributed and each cluster contains an almost equal number of sensor nodes. As a result, the load of the CHs becomes balanced, which ultimately prolongs the network lifetime. Simulation results also demonstrate that the proposed approach can reduce the energy consumption at most 60% compared to LEACH-B protocol.

Keywords: Lifetime, Midpoint algorithm, Hybrid K-Means, centroid selection.

### INTRODUCTION:

A sensor node generally consists of sensors, actuators, memory, a processor and they communicate through a wireless medium. WSNs are deployed to carry out various applications, such as environmental monitoring [1], wildlife habitat monitoring

[2], acoustic monitoring [3], and battlefield surveillance [4]. But these applications raise a few challenges like improving the network lifetime by making the sensor nodes functional for a longer period of time. Figure 1 represents a typical wireless sensor network. The sensor nodes (SN) send the

data packet to the respective cluster heads (CH) which further sends data to the sink or the base station. The nodes can vary from hundreds to thousands.

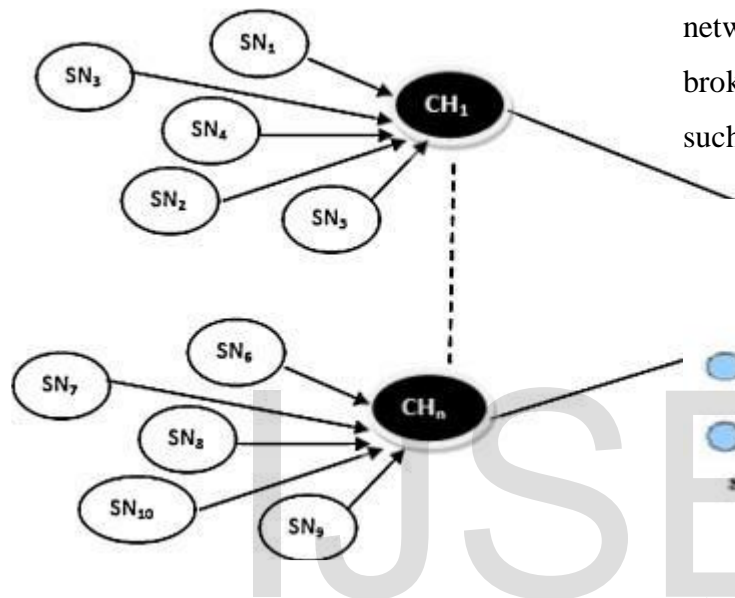


Fig.1. Typical Wireless sensor networks [5]

Sensor nodes or motes in WSNs are small sized and are capable of sensing, gathering and processing data while communicating with other connected nodes in the network, via radio frequency (RF) channel. Architecture of the wireless sensor network [6], Consists of the following components.

(a) *Sensor node*: a sensor node is the core component of the wireless sensor network because it can perform multiple roles in a

network, such as sensing, data processing, data storage and routing.

(b) *Clusters*: Clusters are the organization unit for WSNs. The dense nature of these networks requires the need for them to be broken down into clusters to simplify tasks such a communication.

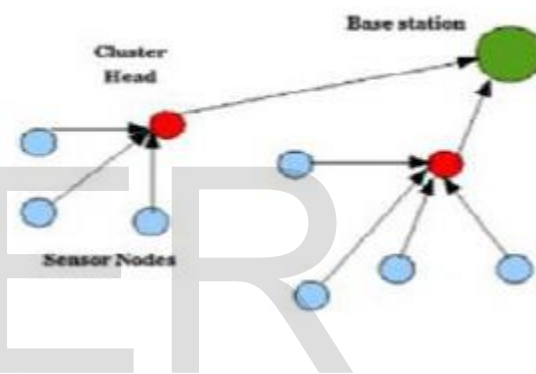


Fig.2. Basic Cluster Structure

(c) *Cluster Heads*: cluster heads are the organization leader of a cluster. They often are required to organize activities in the cluster. These tasks include but are not limited to data-aggregation and organizing the communication schedule of a cluster.

(d) *Base Station*: the base station is at the upper level of hierarchical WSN. It provides the communication link between the sensor network and the end user.

(e) *End-User*: The data in the sensor network can be used for a wide range of applications [3]. Therefore for a particular application may make use of the network data over the internet, using a PDA, or even a desktop computer. All the processing is done at the end user when data from various nodes are collected.

LEACH-B (LEACH-Balanced), at each round, after first selection of cluster head according to LEACH protocol, a second selection is introduced to modify the number of cluster head in consideration of node's residual energy. As a result the number of cluster head is constant and near optimal per round. But, the constant cluster head will not satisfy all the time period.

In this paper, the proposed EECPHK-means protocol improves the initial centroid selection procedure of K-means using midpoint algorithm [7] which produces balanced cluster compared to K-means. It also optimizes CH selection method by considering residual energy as a parameter of CH selection in addition to Euclidean distance used in basic K-means algorithm.

The rest of the paper is organized as follows: Section 2 describes the proposed EECPHK-means protocol. Section 3 shows the experimental results and comparison. Section 4 concludes the paper.

## II. PROPOSED SYSTEM:

### Network model

The following assumptions are made regarding the network model:

- (i) The sensor nodes and BS are all static after deployment.
- (ii) There is only one BS far from the sensing region.
- (iii) Sensors are homogeneous having the same initial energy.
- (iv) After deployment BS knows the geographical information of all sensor nodes.
- (v) Data aggregation happens in each of the CH. The CH ultimately sends aggregated data to the BS.
- (vi) CHs follow single-hop or multi-hop communications depending on the distance from the BS.

### **Algorithm 1: The Hybrid K-means clustering algorithm**

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1) **repeat**

(2) find two objects (clusters) with closest distance among all, and cluster them together.

(3) the value of attributes of new cluster are the average of attributes of two old objects (clusters);

(4) **until** the percentage of hierarchical clusters requested by user is done;

(5) calculate average attribute values of members of clusters that generate from step (1) to (4) as initial cluster centroids;

(6) **repeat**

(7) **for** all objects

(8) **if** the object already appeared in step (2)

**then** the object remain in original cluster;

(9) **else**

Calculate distances between the object and existed clusters

(10) **if** the shortest distance lower than threshold

(11) **then** the object are assigned to the closest cluster

(12) **else**

the object belongs to minor group

(13) **end for loop**

(14) update the centroid attribute value;

(15) **until** no member changes belonging cluster;

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In algorithm 1 describes the hybrid K-Means clustering algorithm.

The working principle of the proposed EECPK-means protocol is divided into three phases as follows:

Phase 1: Initial CH selection.

Phase 2: Balanced cluster formation.

Phase 3: Data communication.

These three phases are described in Algorithm 2, Algorithms 3 and 4 (see Figs. 2 and 3), respectively.

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### **Algorithm 2: Midpoint algorithm for initial CH selection**

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Input:

D = set of n data points.

k<sub>opt</sub> = optimum number of desired clusters

Output:

k<sub>opt</sub> number of initial centroids.

Steps:

- 1: Compute the distance from origin for each data point.
- 2: Sort the distances obtained in step 1. Sort the data points in accordance with the distances.
- 3: Partition the sorted data points into  $k_{opt}$  equal sets.
- 4: In each set, take the middle point as the initial centroid.

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Algorithm 2 describes the midpoint algorithm [9] which has been used for initial CH selection assuming that the data points contain only positive values. Here the centroid of a cluster is a virtual node located at the centre position of the cluster. To maintain the connectivity of the network, residual energy of the CH is checked every round. If the energy of the CH is smaller than the threshold energy, the node having the next ID number is selected as a new CH as in [10]. The newly elected CH informs other nodes about the change of the CH.

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Algorithm 3: Balanced Cluster Formation

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**Input**

$D$  = Set of  $n$  data items

$k_{opt}$  = Optimum number of desired clusters

$E_{threshold}$  = Threshold energy

**Output:**

A set of  $k_{opt}$  clusters

**Steps:**

1. Apply Midpoint method presented in Algorithm 2 to choose  $k_{opt}$  out of  $D$  sensor nodes as initial cluster heads;
2. Repeat
3. Each of the remaining nodes decides to join its nearest CH according to the Euclidean distance.
4. Centroid of each cluster is calculated as
 
$$Centroid(X, Y) = \left[ \frac{1}{S} \sum_{i=1}^S x_i, \frac{1}{S} \sum_{i=1}^S y_i \right]$$
5. After cluster formation, based on the distance from the centroid, an ID number is allotted to each node of a cluster, assigning smaller number to the closer one.
6. **For** all selected cluster Heads
7. **If** (Residual energy of cluster head  $\geq E_{threshold}$ )
8. **Then**
9. The node will remain as cluster head
10. **Else**
11. Check ID number of all the sensor nodes in that cluster

12. The node in the next order of ID number is selected as a new CH.

**13. End if**

**14. End for**

15. The newly elected CHs inform other nodes about the CHs change.

16. Until the cluster heads are not changed any more.

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Algorithm 3 describes the balanced cluster formation phase. In this approach, an estimation of threshold residual energy is given, which was not addressed in [10]. Here the threshold energy is the amount of energy required to receive, aggregate and transmit the average number of sensor nodes in the cluster.

### SIMULATION RESULT

For simulating the proposed EECPHK-means protocol, MATLAB R2015a and C language have been used. Considering  $dBS = 100$ , the number of desired CH = 4 is obtained and considering  $dBS = 85$ , the number of desired CH = 5 is obtained, having 100 sensor nodes in  $100 \times 100$  m<sup>2</sup> sensing region. Simulations have been performed for both 4-cluster and 5-cluster

networks. The proposed EECPHK-means protocol has been compared with LEACH-B protocol [11] used in WSN with respect to cluster formation.

### Parameters for Simulation

Similar random 100-node networks and radio models are used with LEACH. This paper set the following parameters for Simulation:

- 1) Energy required in sending or receiving 1 bit:  $E_{elec} = 50 \text{ nJ/bit}$
- 2) The amount of data sent by nodes each time:  $k = 200 \text{ bit}$ .
- 3) The initial energy of every node:  $E = 0.5 \text{ J}$
- 4) Compress ratio during data fusion:  $r = 0.7$
- 5) Energy consumed in every bit data fusion:  $E_A = 50 \text{ pJ/bit}$
- 6) Area:  $100 \times 100$
- 7) The location of Sink: (5, 5)
- 8) The percentage of cluster head:  $p = 0.05$
- 9) The number nodes:  $n = 100$ .

### Figures and Analysis

The network performance is measured by its life time. Figure 3 shows the system lifetime using the EECPHK-means protocol and LEACH-B algorithm. As shown in the figure, nodes in LEACH-B protocol begin to die after about 800 rounds, and almost all

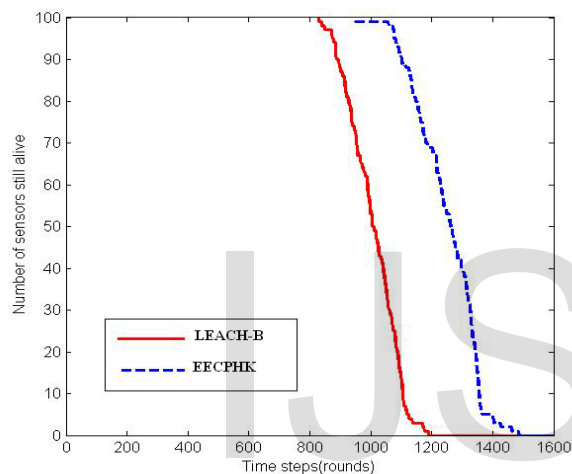


Fig 3: System lifetime

nodes die when it comes to 1200 rounds. While in EECPHK-means, nodes begin to die after about 1000 rounds, and all nodes die after 1500 rounds. Therefore, the lifetime of EECPHK-means has obvious longer than the LEACH-B protocol which proves that the improved algorithm has extended the system lifetime effectively.

### III. CONCLUSION

In this paper, with the research of the LEACH-B protocol, a novel protocol called EECPHK-means is put forward. This enhanced algorithm has overcome the shortcoming of the original protocol by taking the node's residual energy into consideration and keeping the constant and near optimal number of cluster heads at each round.

The simulation result shows that EECPHK-means provides better energy efficiency and longer network life span than LEACH-B.

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